

I, Robot: Blurring the Lines between Mind, Body and Machines

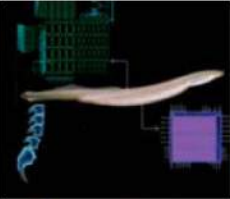
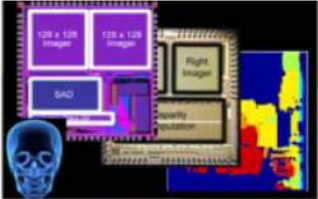
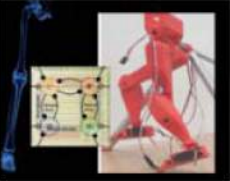
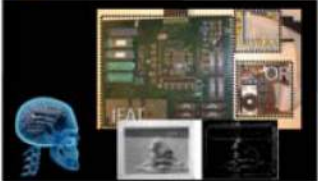
Ralph Etienne-Cummings

Dept. of Electrical and Computer Engineering and Computer Science
Johns Hopkins University

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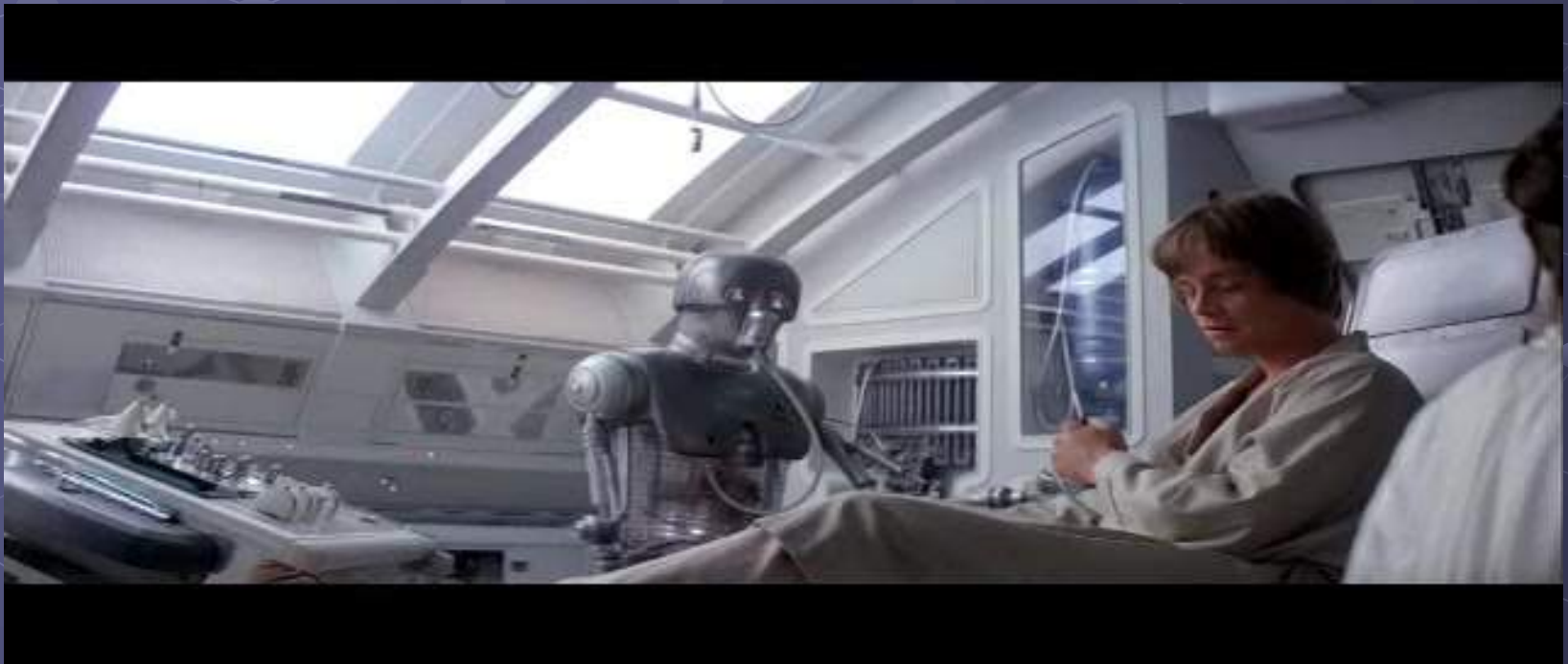
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Computational Sensory-Motor Systems Lab

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The Motivation

- Fully neurally integrated prosthetics
 - **Thoughts** to action (decoding of intent)
 - Sensors to **feeling** (encoding of reaction)
 - **Knowing** location of limbs (representing joint space)

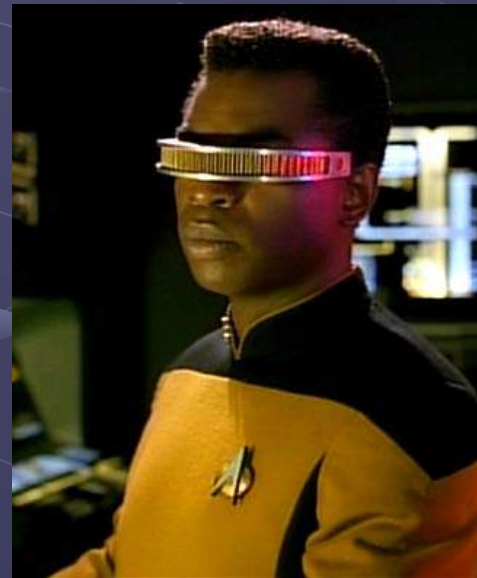


The Motivation

- Enhancing Human Capabilities
 - **Memory** Extensions (Storage/Retrieval of Memories)
 - **Perceptive** Extension (Hyper Spectral Optics/Acoustics)
 - **Direct Brain-Brain** Communications



Johnny Mnemonic, TriStar Pictures, 1995

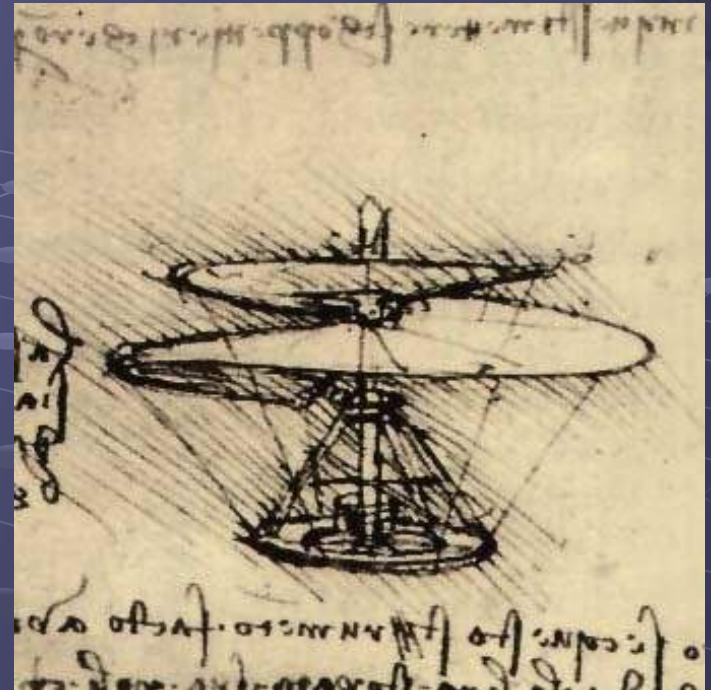


Star Trek, Next Generation, Paramount Studios, 1987

Nature Inspires Machines

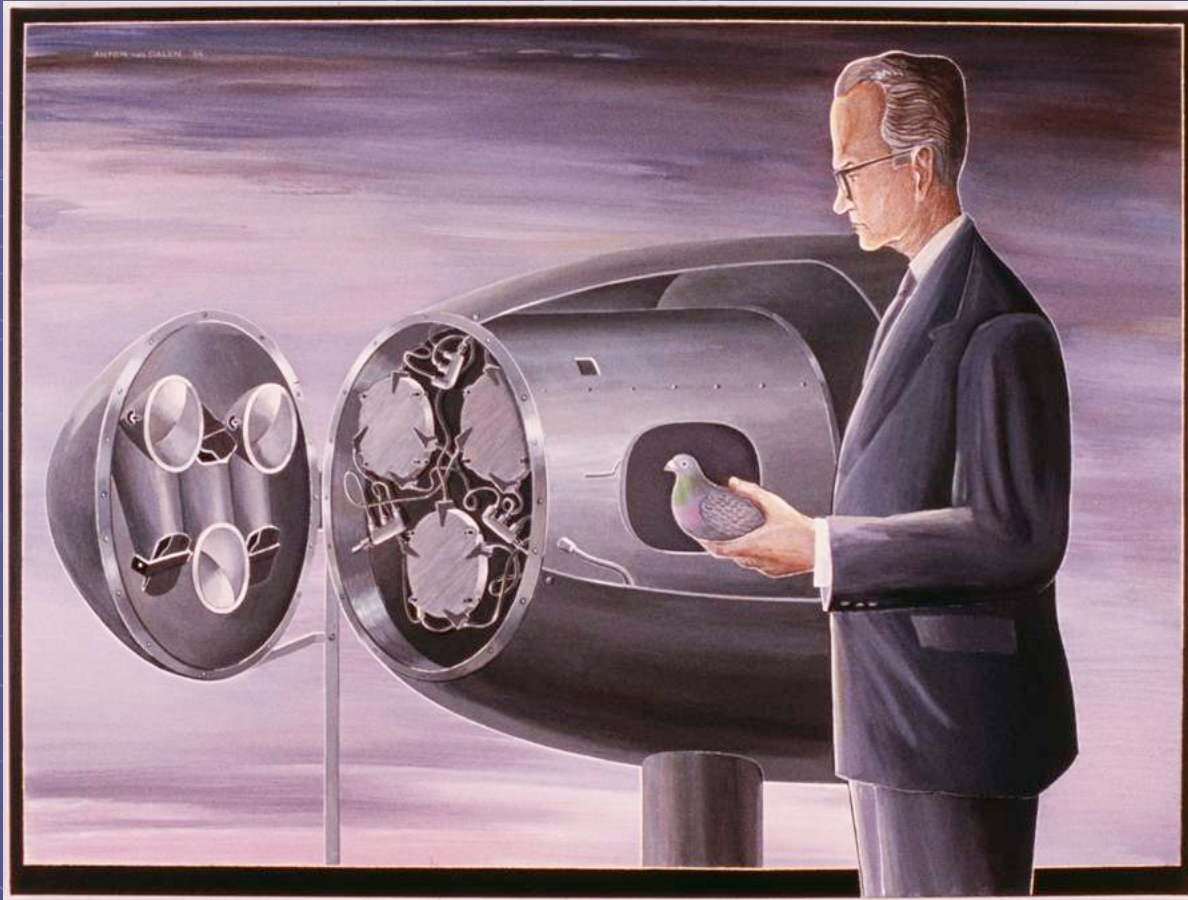


Antoni Gaudi, *Casa Mila*, 1906 – 1910
“Form”



Leonardo da Vinci, *Helicopter*,
1452 – 1519
“Function”

Nature in the Loop with Machines

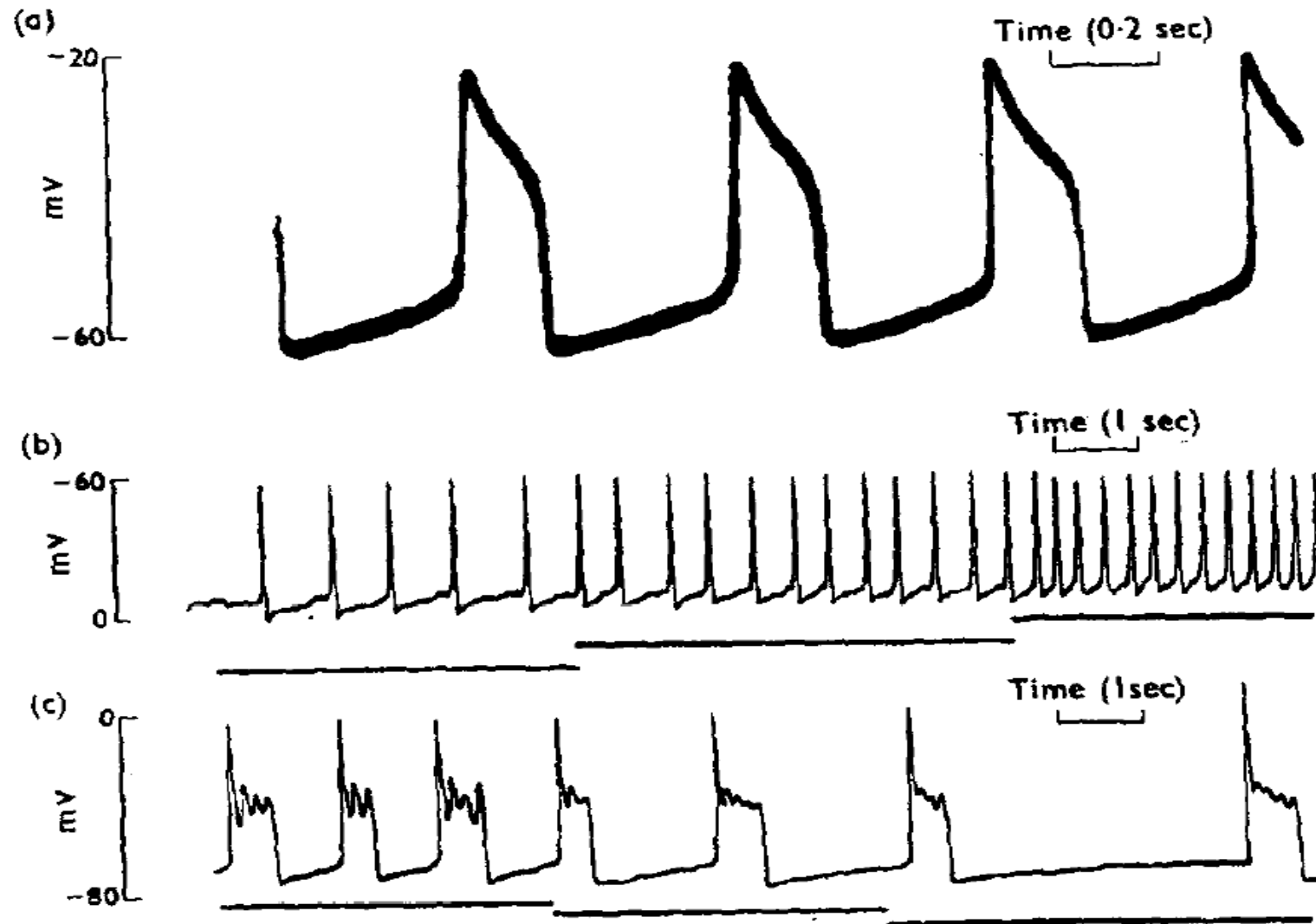


B. F. Skinner by Anton van Dalen



Smithsonian Institute

Nature's Inspiration

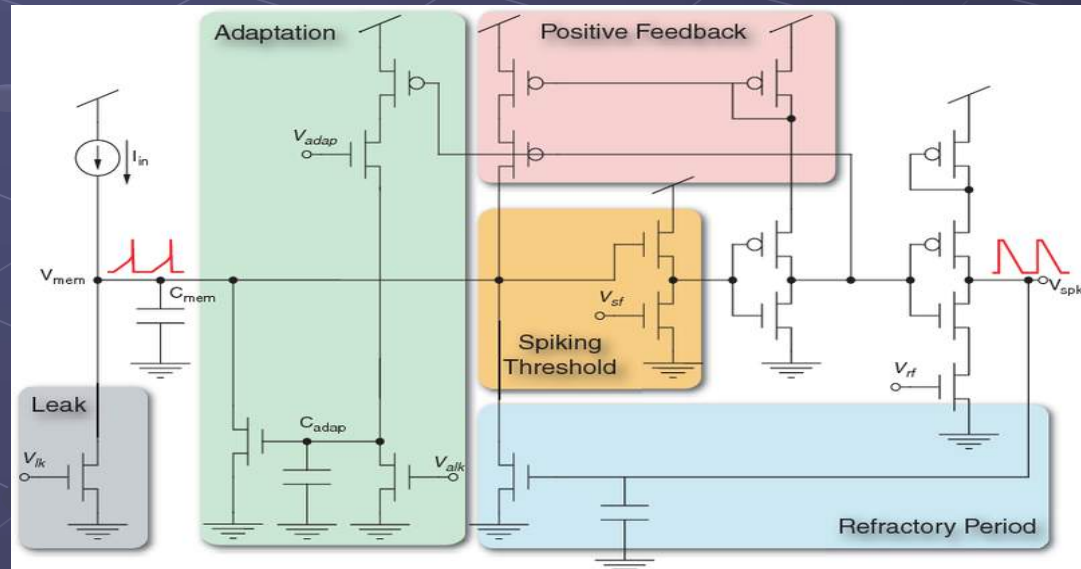
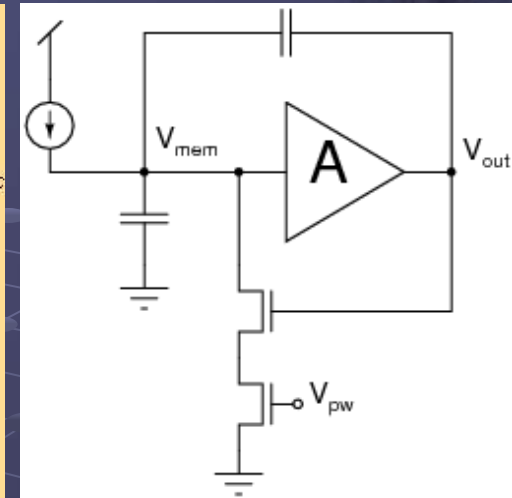
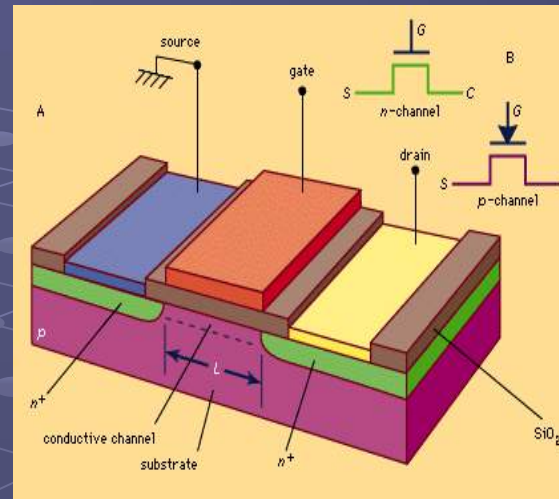
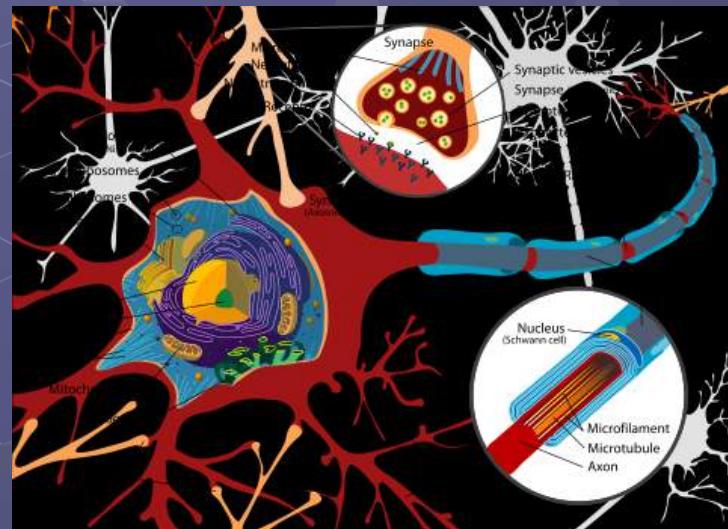
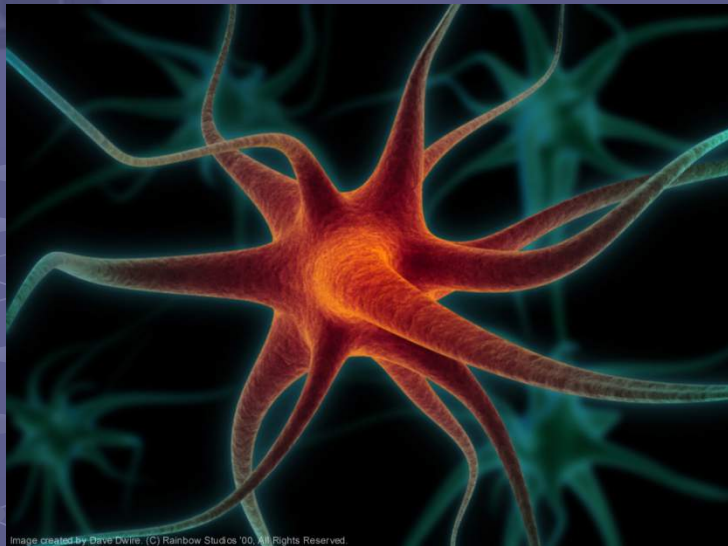


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August 2012

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Nature's Inspiration



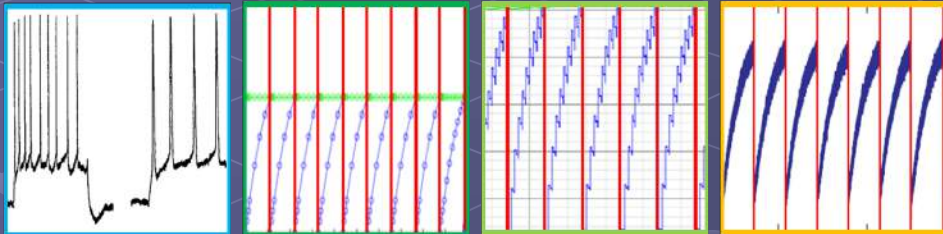
Paul Mueller, Carver Mead, *Neuromorphic Circuits*, 1986 - 1990

After wikipedia.com

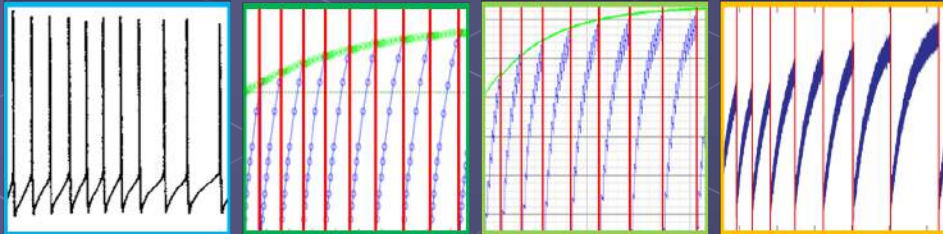
Large Scale Brains in Silicon



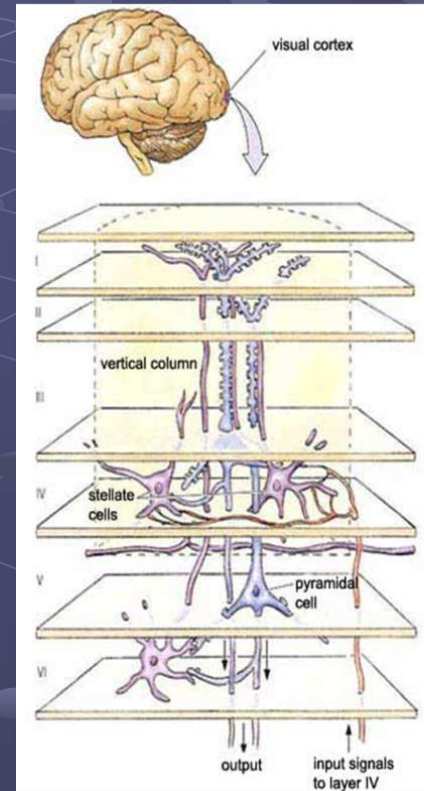
• Tonic Spiking



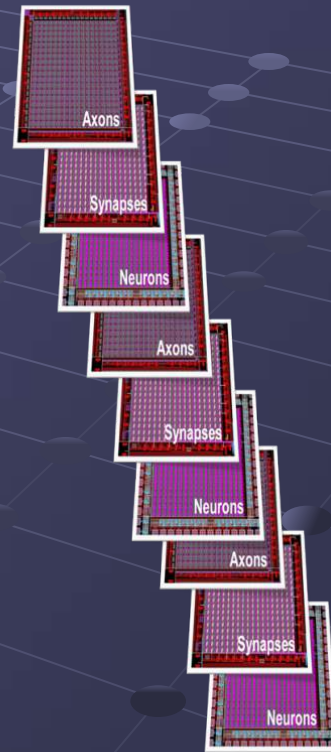
• Spike Frequency Adaptation



F. Fofonowicz et al., IEEE INN, 2011



Interconnected with Through-Wafer Vias



3D IFAT (Johns Hopkins), 2008 - present



Presentation Outline

● Cameras That Work Like Our Eyes

- The biological visual system
- Silicon eyes
- Making the Blind See

● Restoring Walking After Spinal Cord Injuries

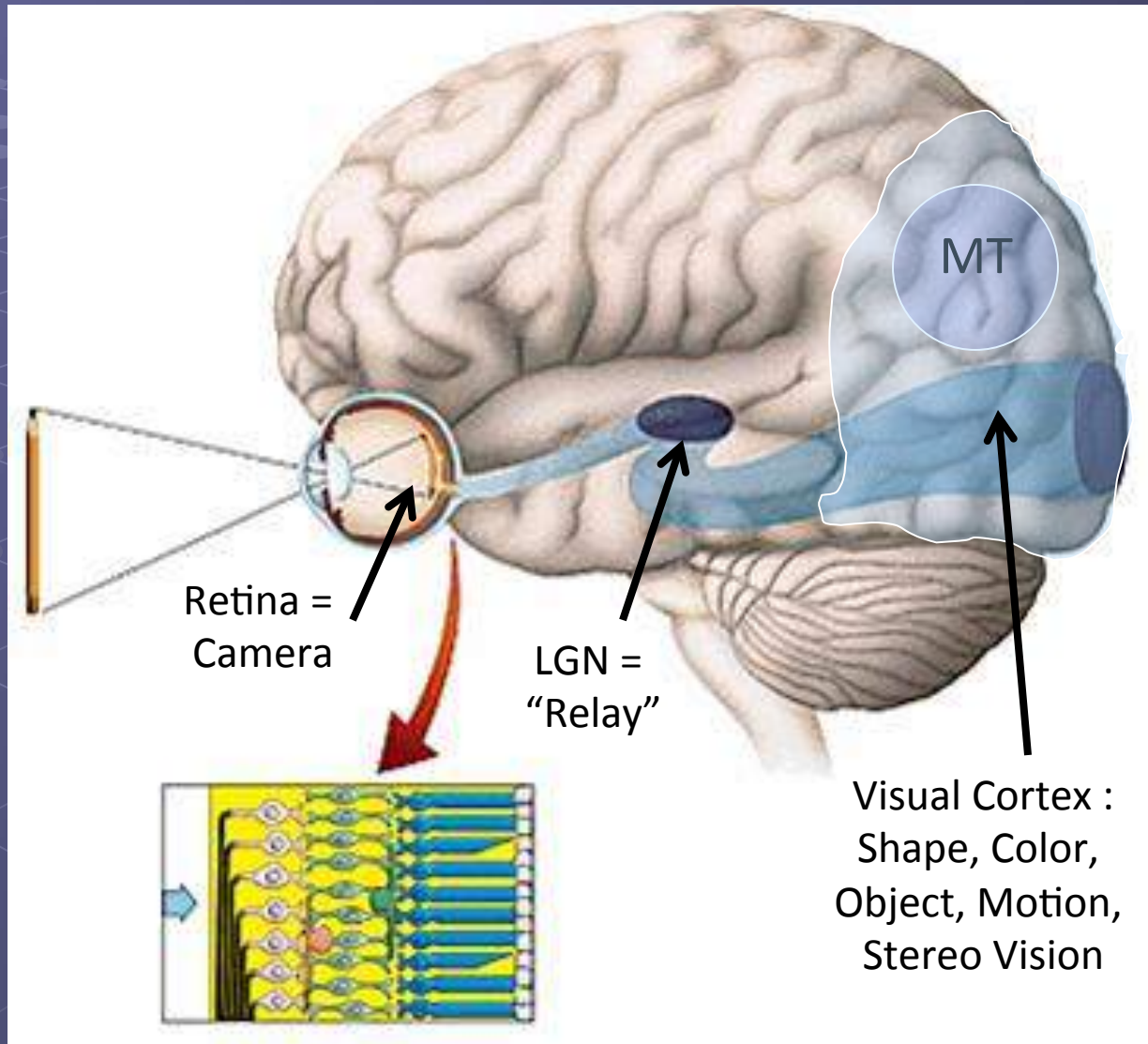
- The biological locomotion system
- Silicon model of spinal cord circuits
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● Replacing Limbs with Neurally Integrated Prosthetics

- High degree of freedom prosthetic limbs
- Closed loop control

● Conclusions

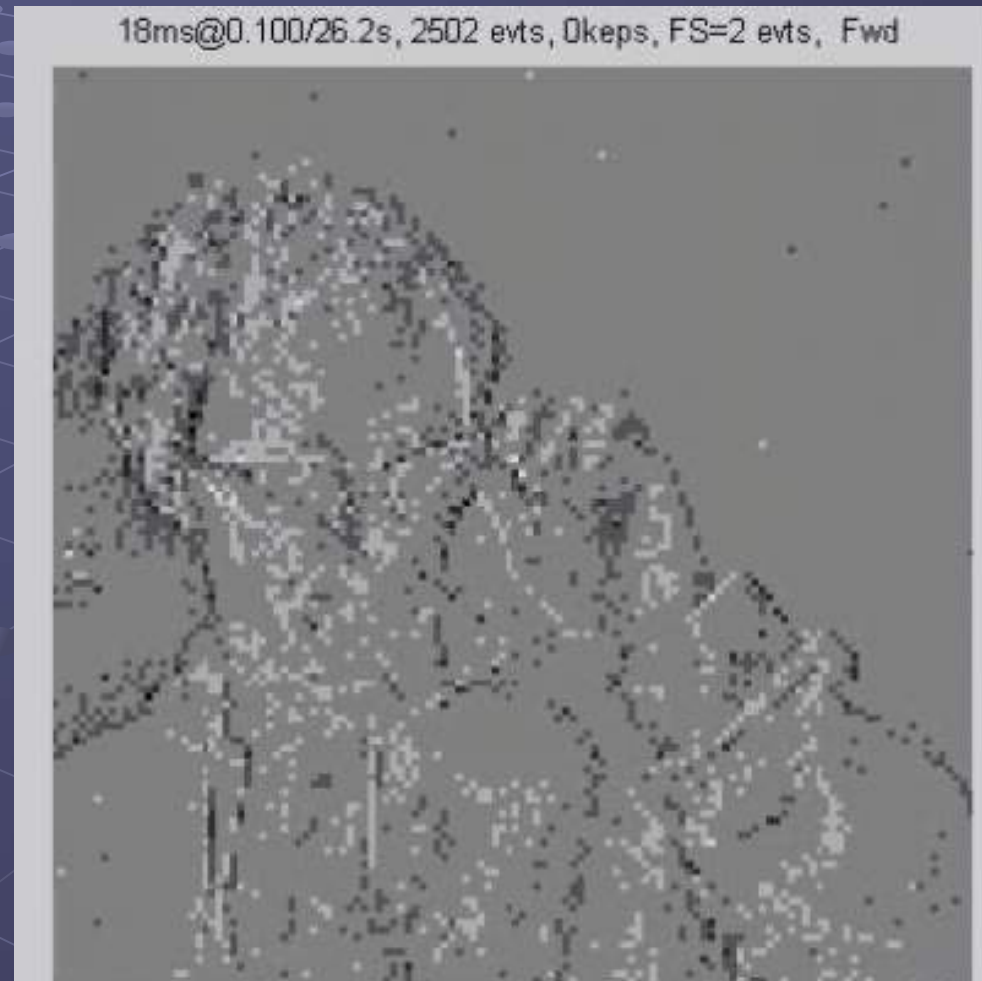
Visual Processing in Humans



Retinal Prosthetics and Retinomorphic Image Sensors

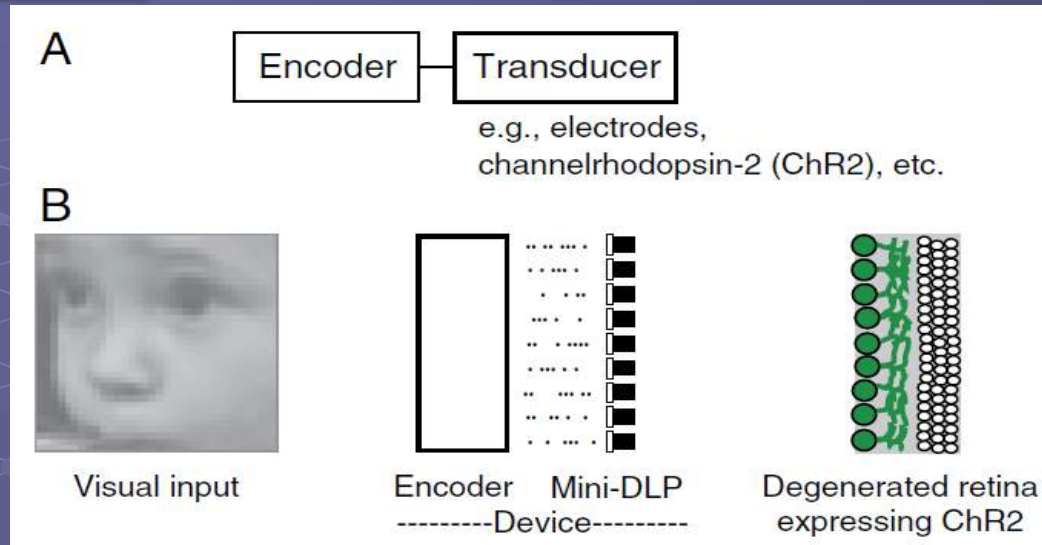


Argus 2.0 (FDA Approved)

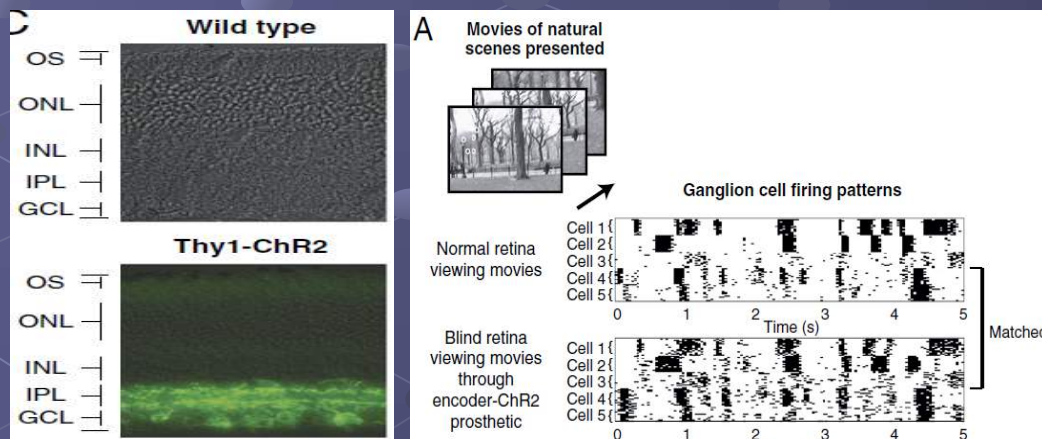
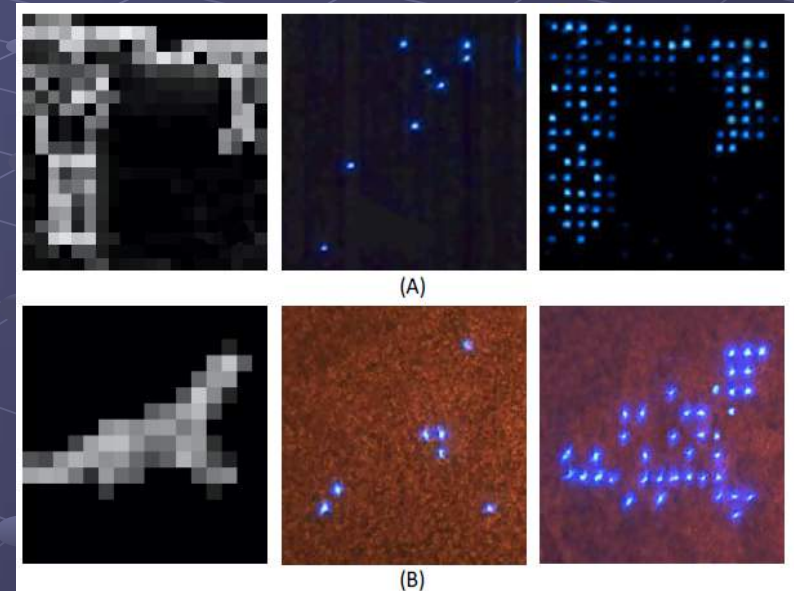


Delbruck et al, ETHZ, 2008

Retinal Prostheses of the Future



LED Chip for Optogenetic Stimulation



Deganaar et al., *IEEE TBME*, 2013
U. Newcastle, UK

Nirenberg & Pandarinath, *PNAS*, 2012
Cornell U.



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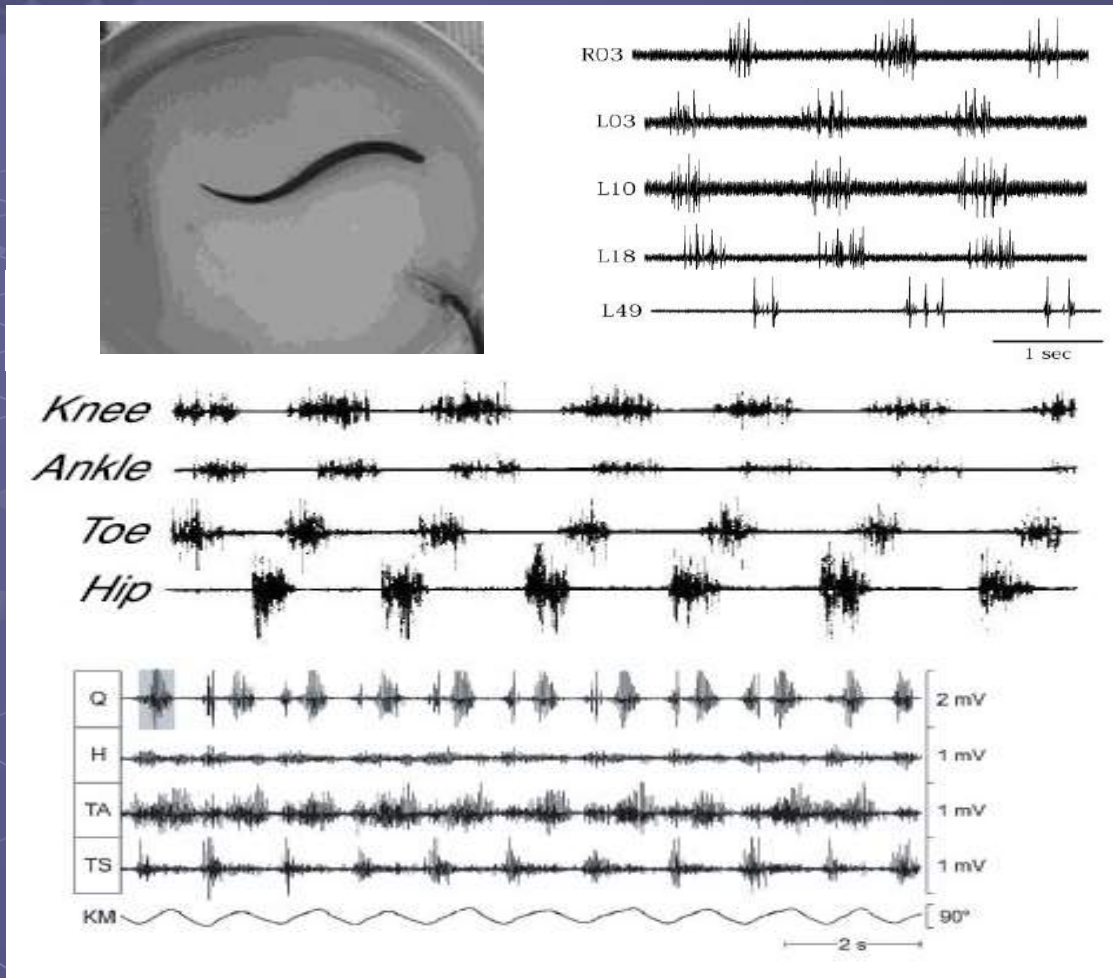
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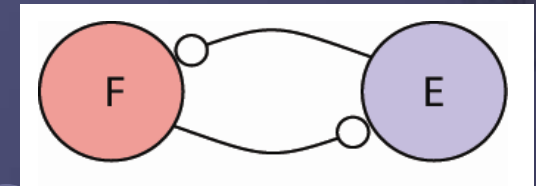
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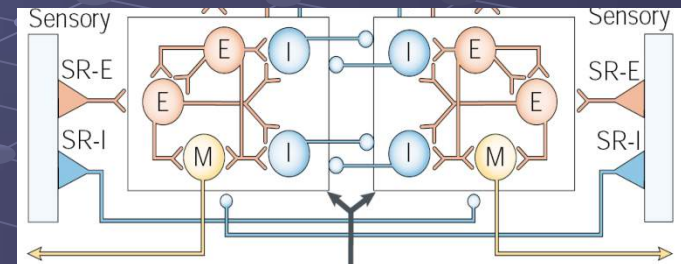
Central Pattern Generation (CPG) in Action



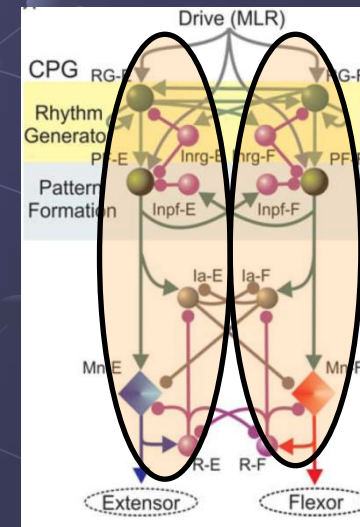
Source: Mellen et al., 1995;
Grillner & Zangger, 1984; Dimitriavic & Minassian et al.,
2004



Source: T. Graham Brown, 1911



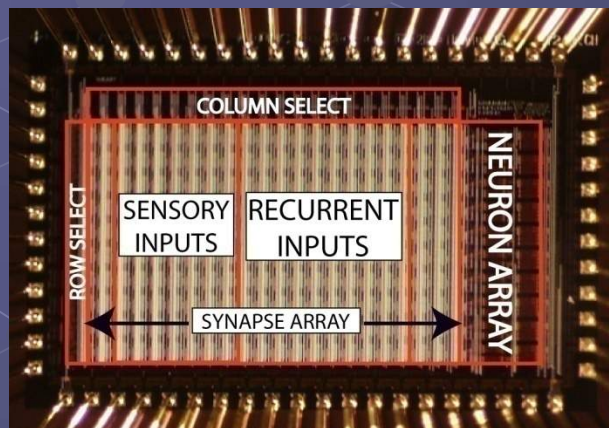
Source: Grillner, Nat Rev Neurosci, 2003



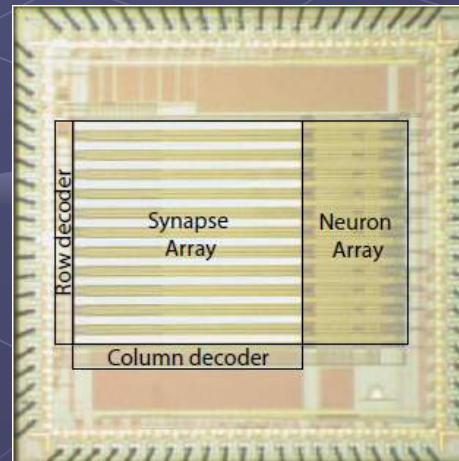
Source: Rybak et al., J Physiol, 2006

A Piece of the Spinal Cord on a Computer Chip

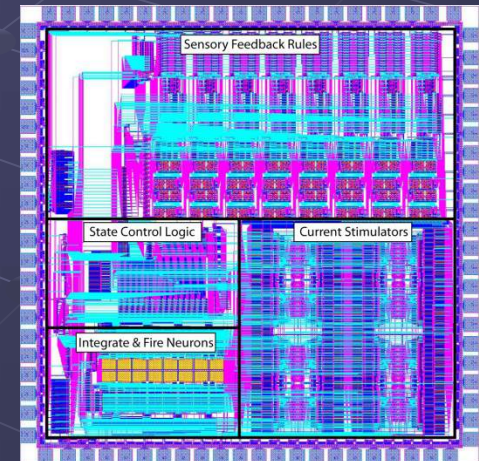
- Prescribe motor output based on pre-defined gait and current sensorimotor state
- Measure biological motor circuits all times and predict next desired state in order to effectively control it
- Build a silicon model of biological spinal circuits: neuromorphic silicon CPG chip (SiCPG) or Locomotion Processor Unit (LPU)



CPGv2 (Tenore et al., 2004)

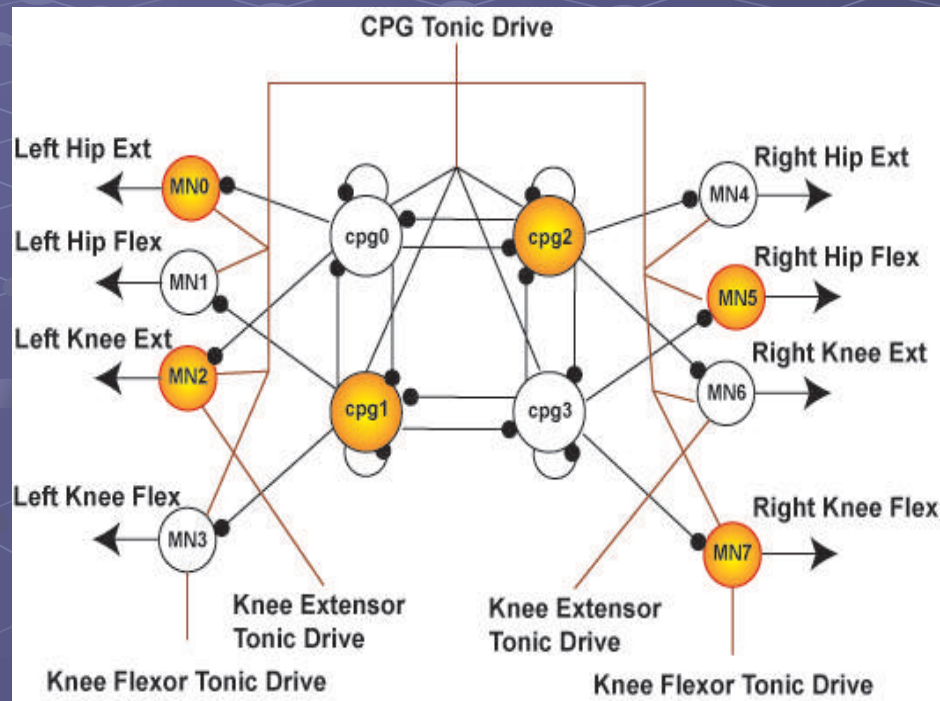


CPGv3 (Tenore et al., 2006)

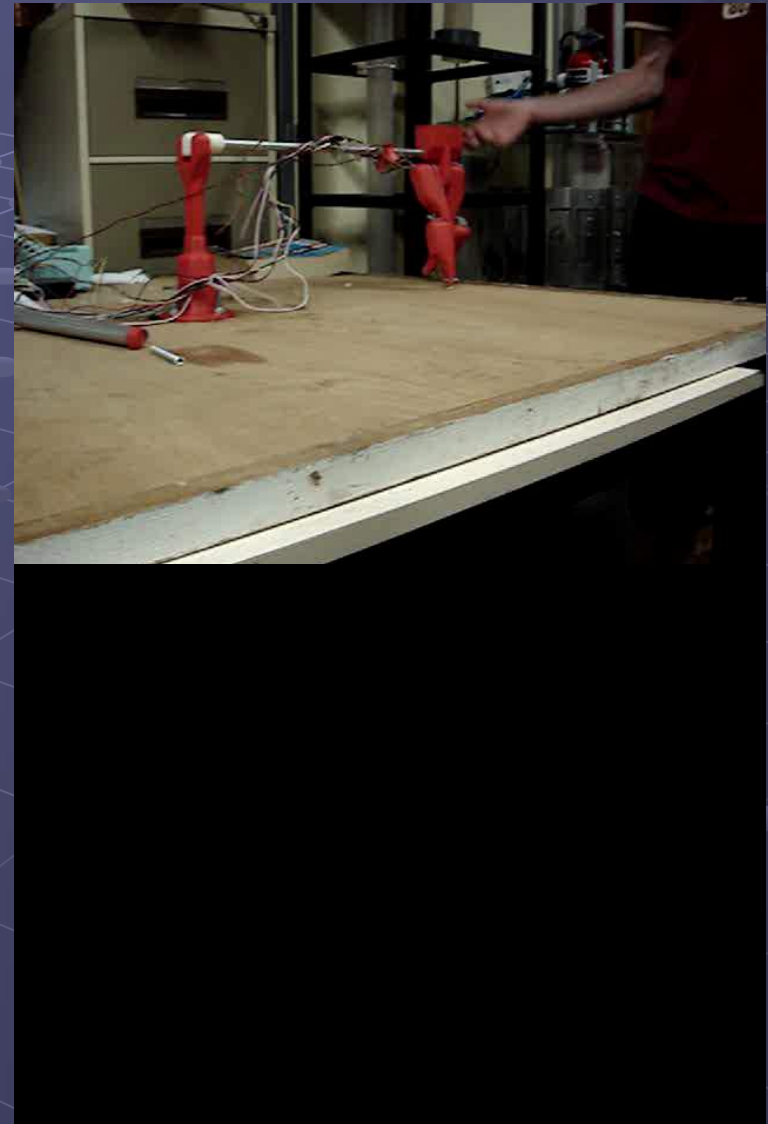


LPU (Mazurek et al., 2011)

Making a Robot Walk with CPG Chip



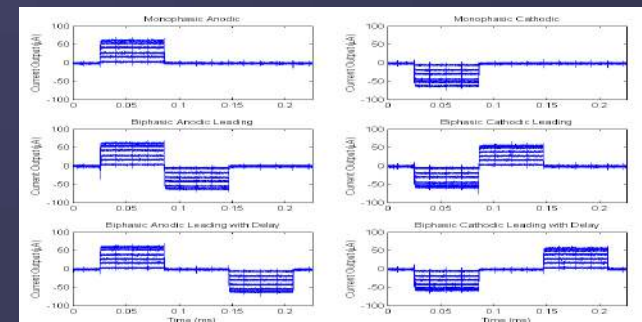
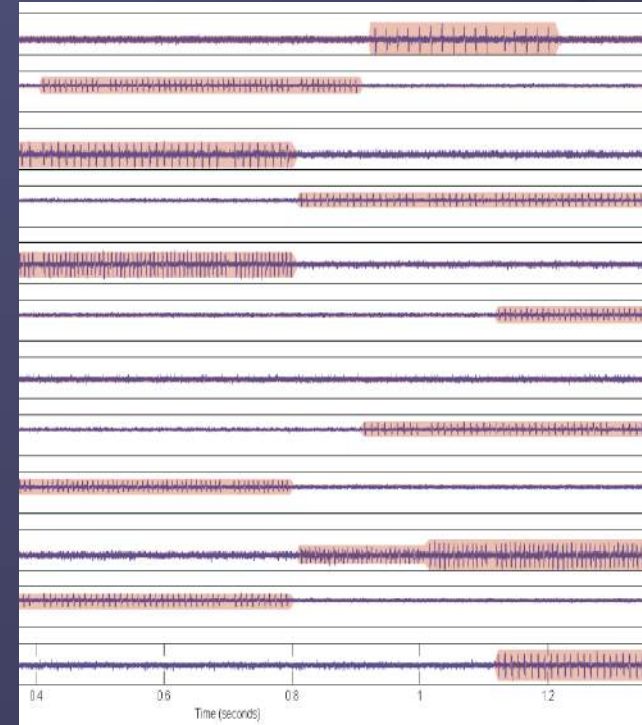
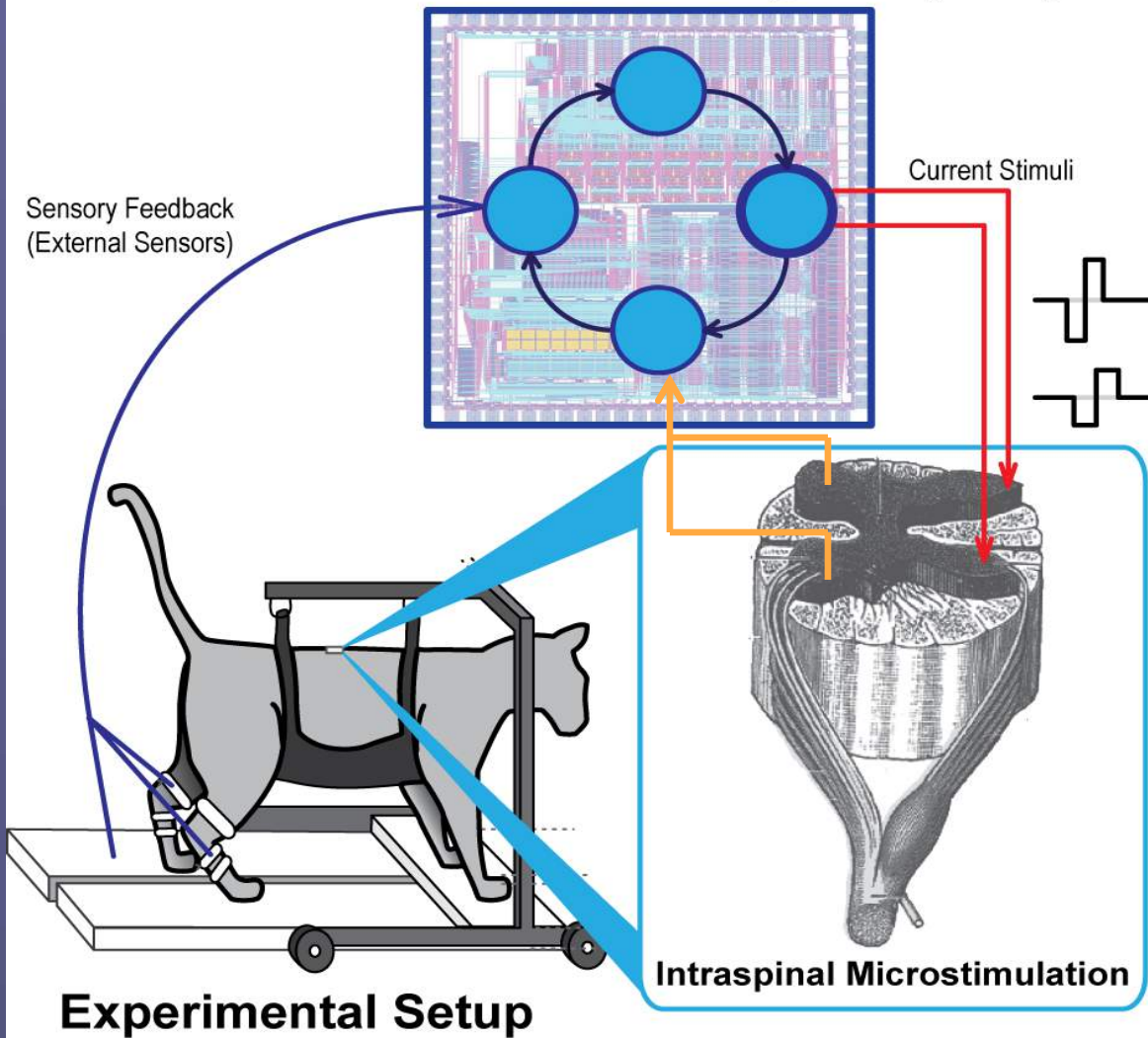
Lewis et al., 2005



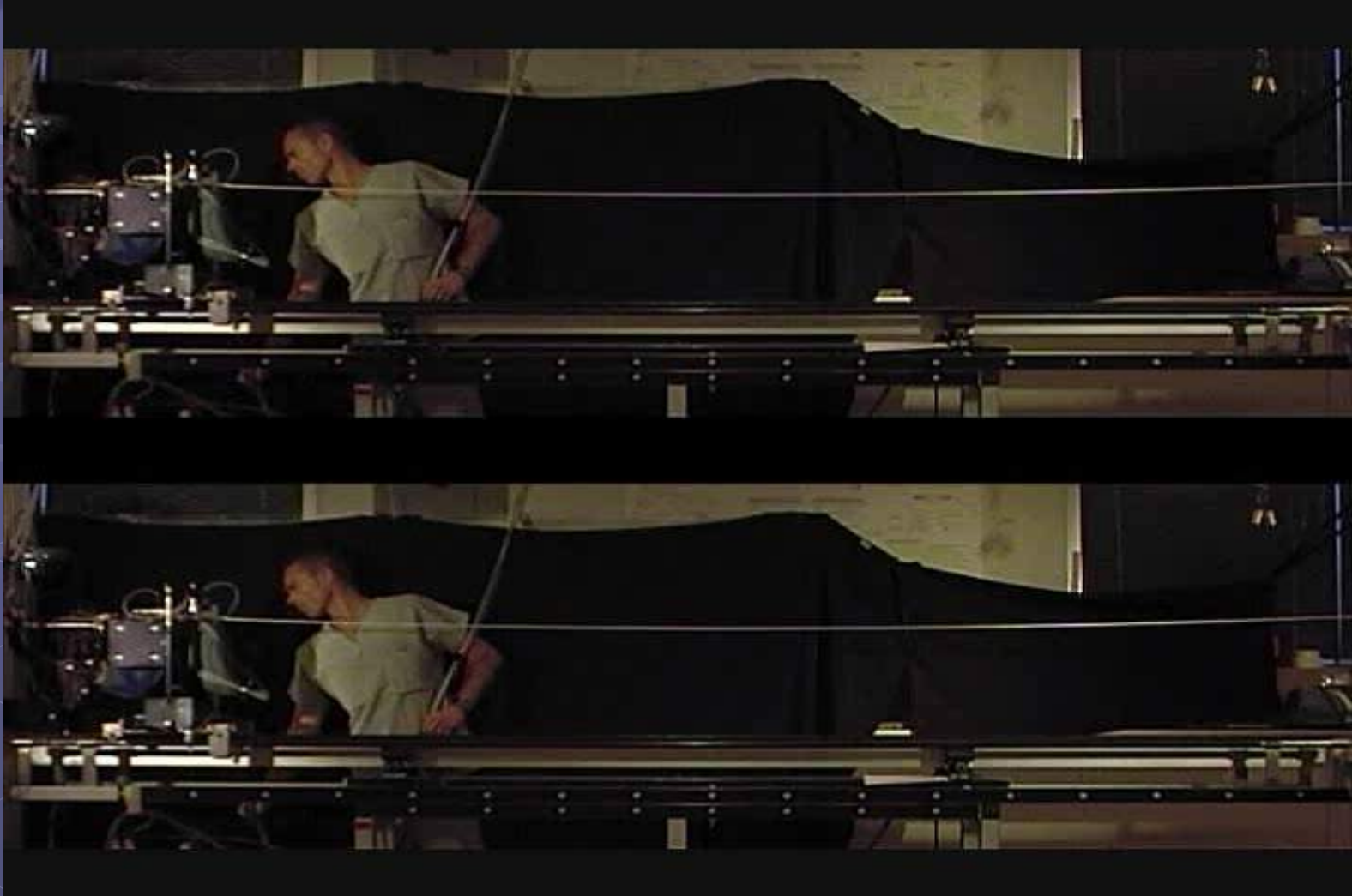
Lewis et al., 2005,2012; Russell, Orchard et al, 2007

Reactivating the Spinal Cord after Injury

Locomotion Processing Unit (LPU)

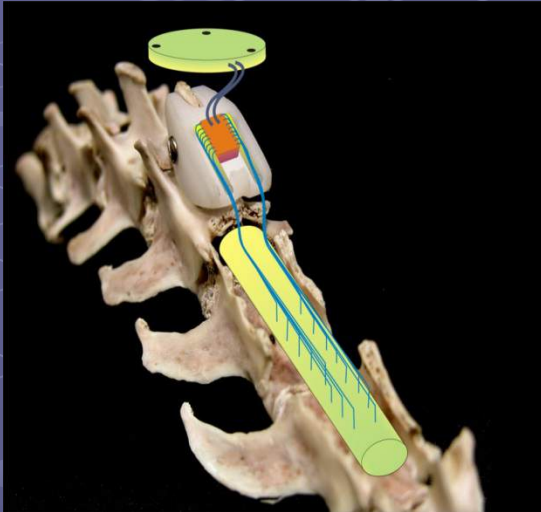


Results: Restoring Locomotion in a “Paralyzed” Cat

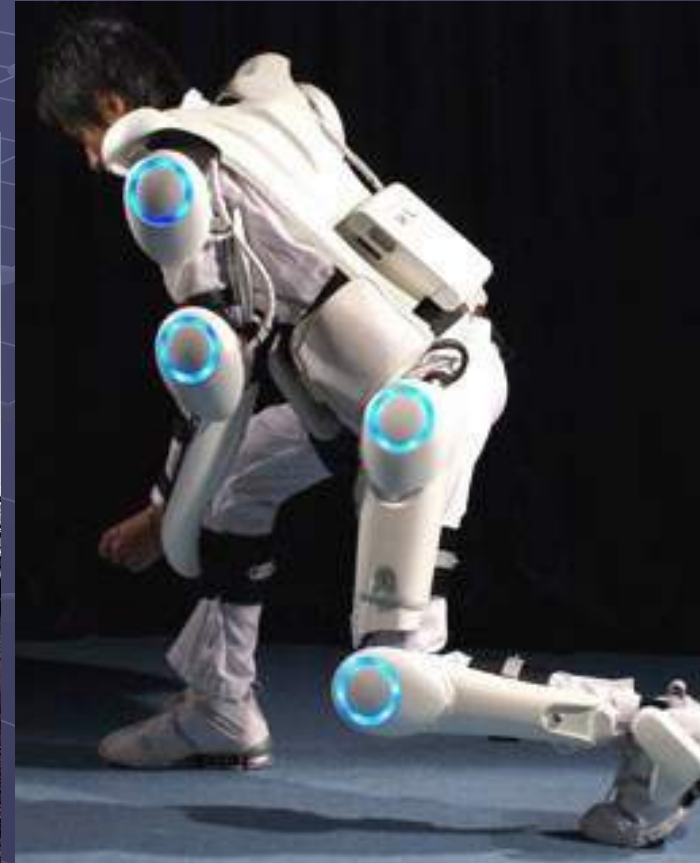


Mazurek et al., 2011
Mushahwar et al, 2011

Implanting the Controller onto The Spinal Cord



Mushahwar et al., 2011



Cyberdyne, Inc.



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Replacing Limbs: Nerve Reinnervation Prosthetic Arm



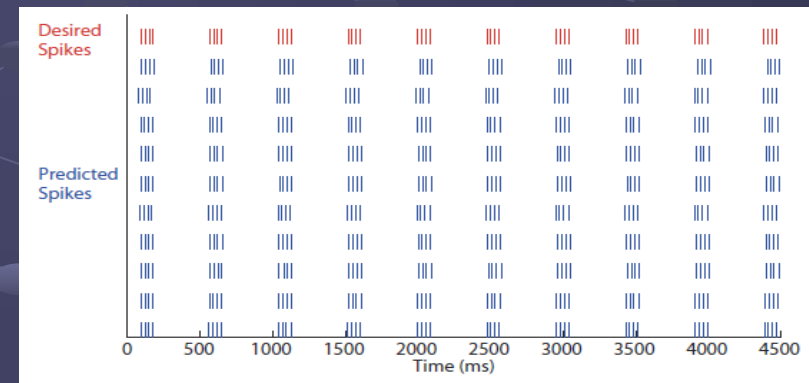
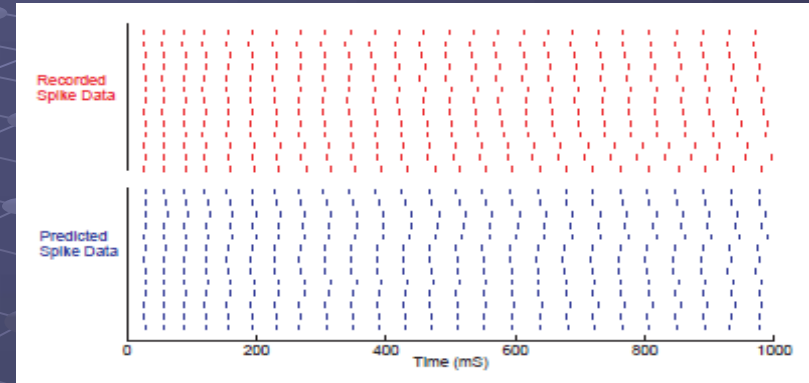
Source: Johns Hopkins U., Applied Physics Lab, RP 2009

Replacing Limbs: Neurally Integrated Prosthesis



Source: Etienne-Cummings & Thakor Labs (Johns Hopkins), Schieber Lab (Rochester) RP 2009

Encoding Sensory Feedback to the Peripheral Nerve

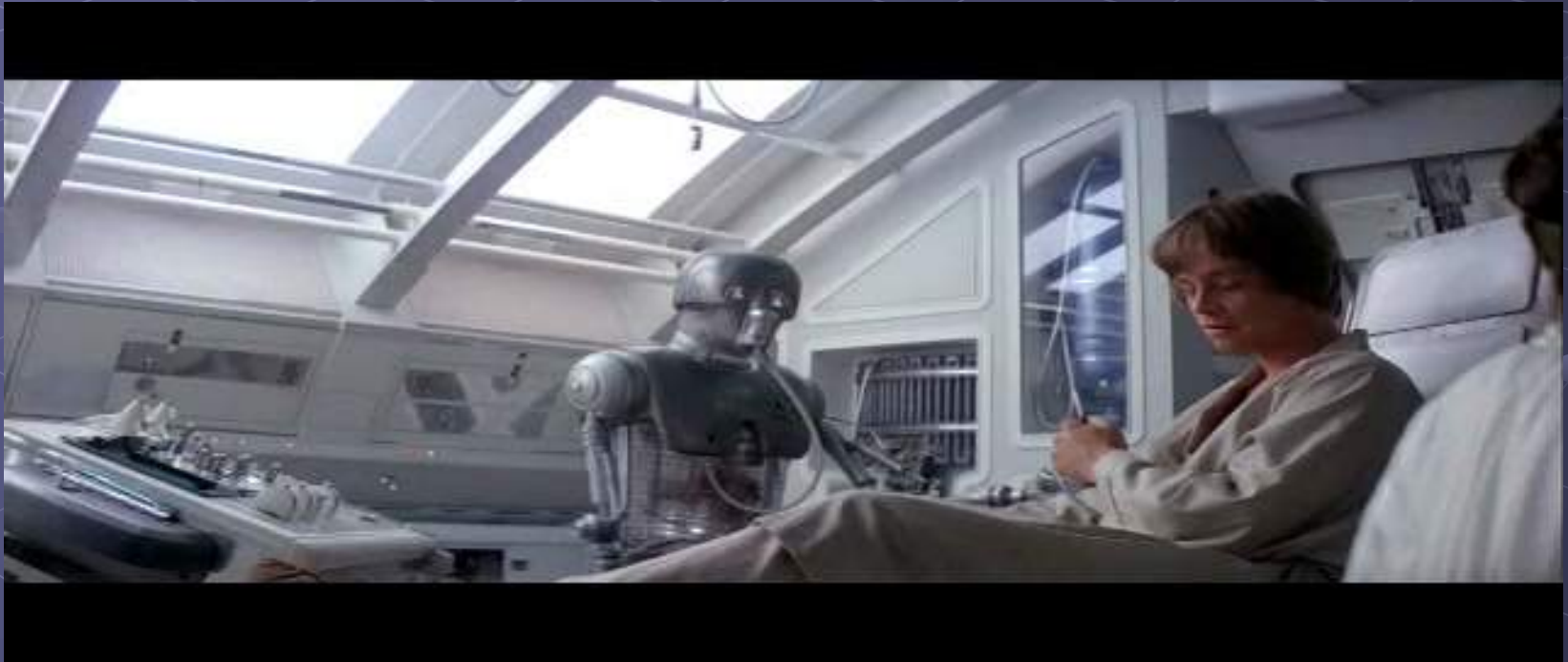


Modeling the SA-1 Peripheral Nerve Fiber *in silico*
Source: Etienne-Cummings (Johns Hopkins) &
Bensmaia (Chicago) Labs

Bensmaia et al., IEEE TBioCAS, 2009
Russell et al, IEEE TBioCAS, 2010 – 11
Russell et al, IEEE TNN, 2010
Russell et al, Neural Comp., 2011

Replacing Limbs: Neurally Integrated Prosthesis

- Acquisition of electrophysiological signals involved in generation of movement
- Extraction of movement-related information from biosignals
- Provide sensory information to the nervous system



Source: Johns Hopkins U., Applied Physics Lab, RP 2009



Conclusion

- The line between mind, body and robotics are quickly blurring and may be disappearing
- In the future we will be able to use electronics and robotics to **seamlessly** mitigate injuries and enhance human capabilities
- Requires basic, computational and applied scientific research in neuroscience and psychology
- **Collaborations** between engineers, biologist and clinicians needed to realize the dream



Acknowledgements

- Various ONR Awards
- Various NIH Awards & Neuroengineering Training Grant
- Various individual NFS Awards
- NSF Graduate Research Fellowships
- DARPA Revolutionizing Prosthetics
- Telluride Neuromorphic Engineering Workshop
- NSF ERC CISST at JHU
- Various AFRL and ARL Awards
- Alberta Heritage Foundation for Medical Research